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Leech

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(54) **GOLF AID INCLUDING HEADS UP DISPLAY**

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A63B 24/00	(2006.01)
A63B 71/06	(2006.01)

(52) **U.S. Cl.**

CPC ***A63B 69/36*** (2013.01); ***A63B 24/0003*** (2013.01); ***A63B 71/0619*** (2013.01); *A63B 2024/0056* (2013.01); *A63B 2069/3602* (2013.01); *A63B 2071/0647* (2013.01); *A63B 2071/0666* (2013.01); *A63B 2220/13* (2013.01); *A63B 2220/20* (2013.01); *A63B 2220/30* (2013.01); *A63B 2220/35* (2013.01); *A63B 2220/806* (2013.01)

(58) **Field of Classification Search**

USPC 473/199, 223, 407

See application file for complete search history.

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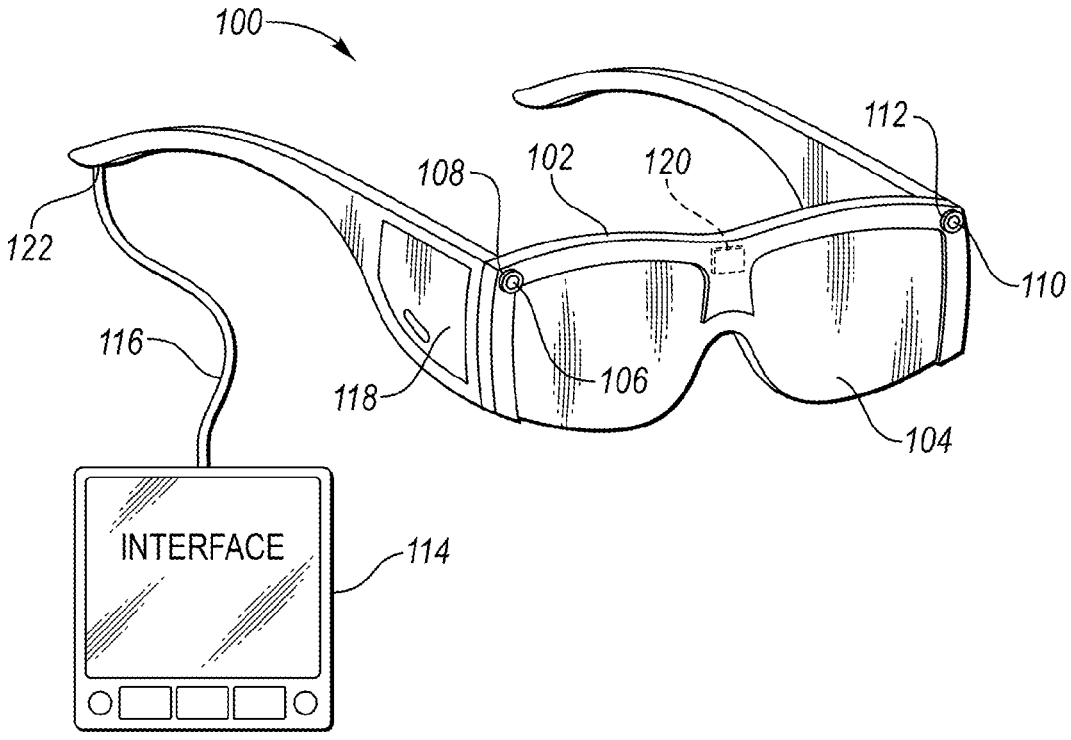
(57) **ABSTRACT**

A golf aid including a practice mode for use while hitting a plurality of golf balls with a golf club includes a golf ball tracking system, a heads up display, and a processor. The golf ball tracking system tracks a plurality of golf ball trajectories, each corresponding to a respective golf ball being hit by the golf club. The heads up display is configured to be worn on the user's head and display an image within a field of view of the user. The processor is configured to compute one or more shot statistics for each one of the plurality of trajectories, display the one or more computed shot statistics and a plurality of trajectory traces within the field of view of the user.

20 Claims, 9 Drawing Sheets



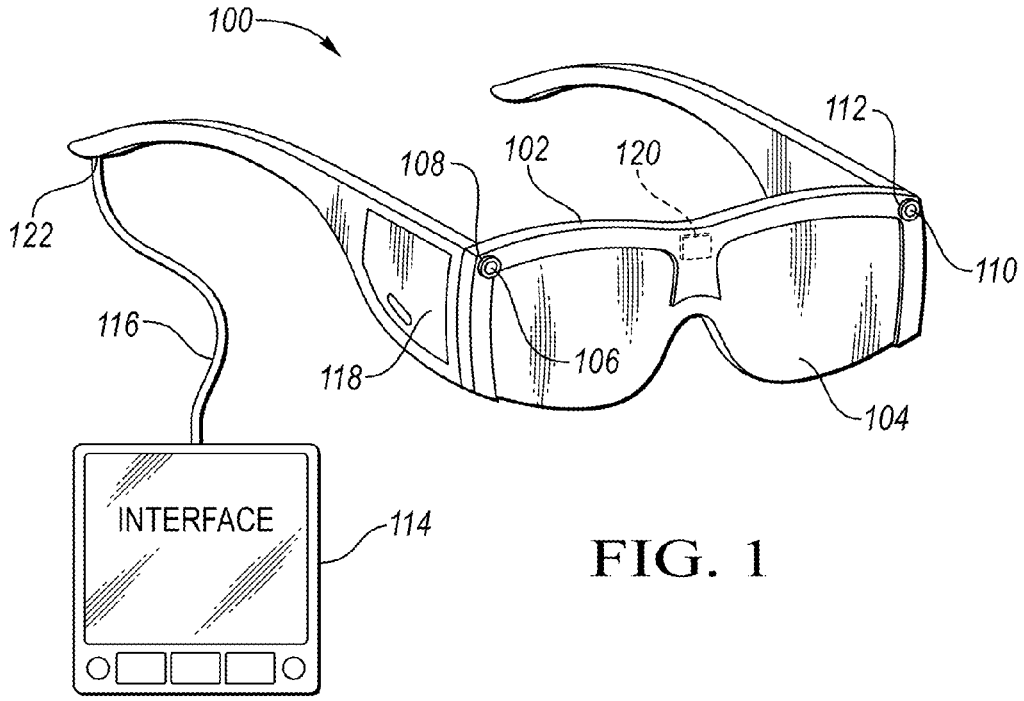

100
112
108
102
120
122
110
116
106
118
104
INTERFACE
114

FIG. 1

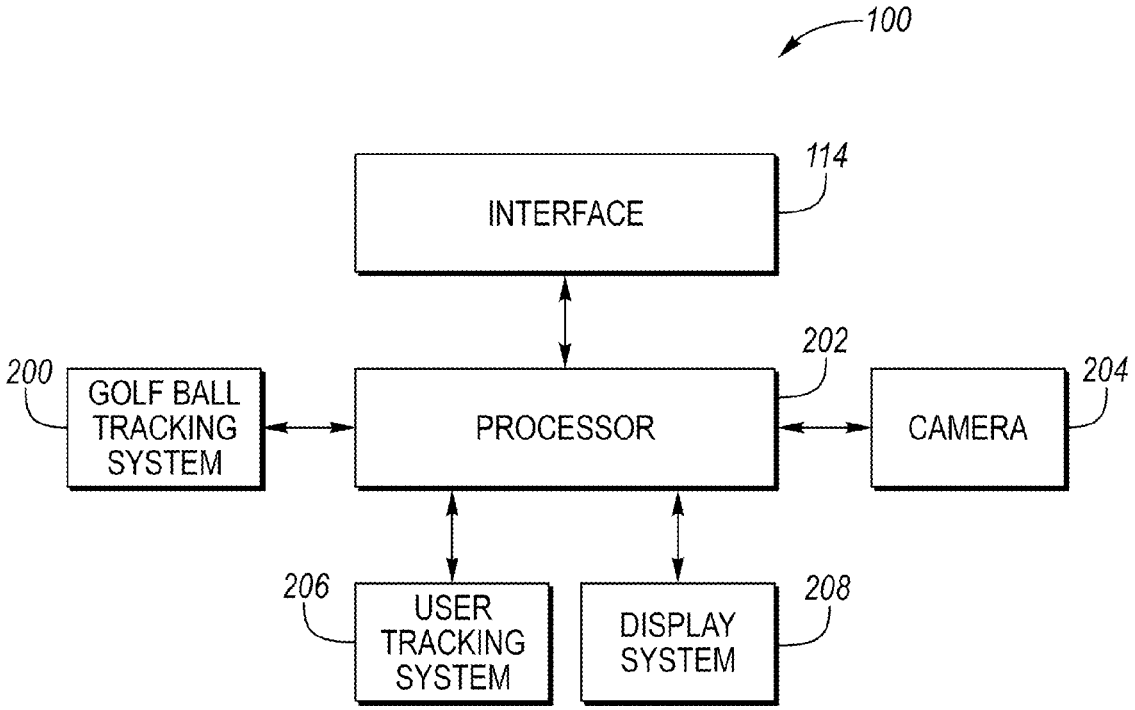

100
114
INTERFACE
202
200
GOLF BALL TRACKING SYSTEM
PROCESSOR
CAMERA
204
206
USER TRACKING SYSTEM
DISPLAY SYSTEM
208

FIG. 2

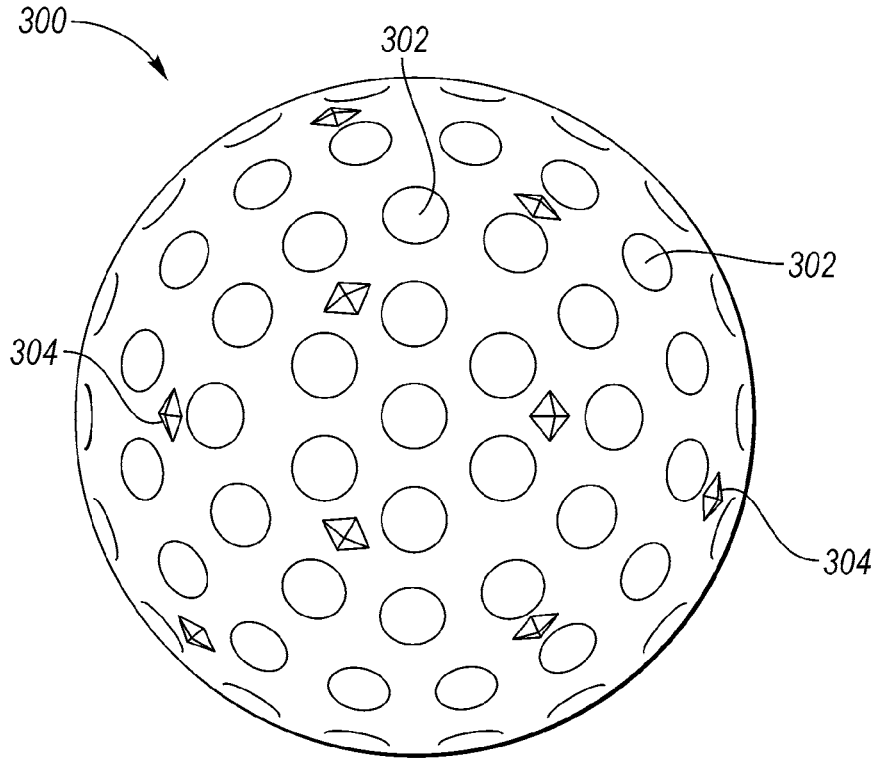


FIG. 3

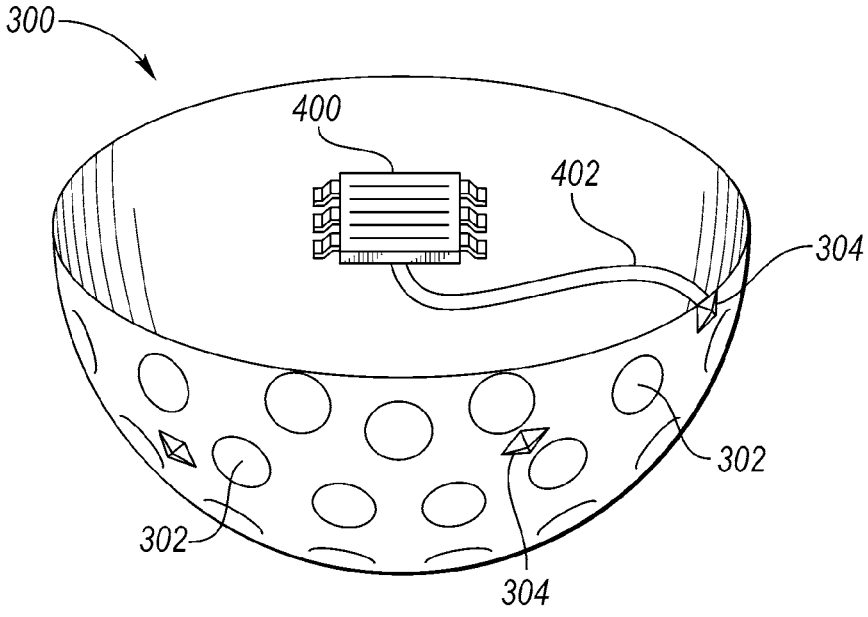


FIG. 4

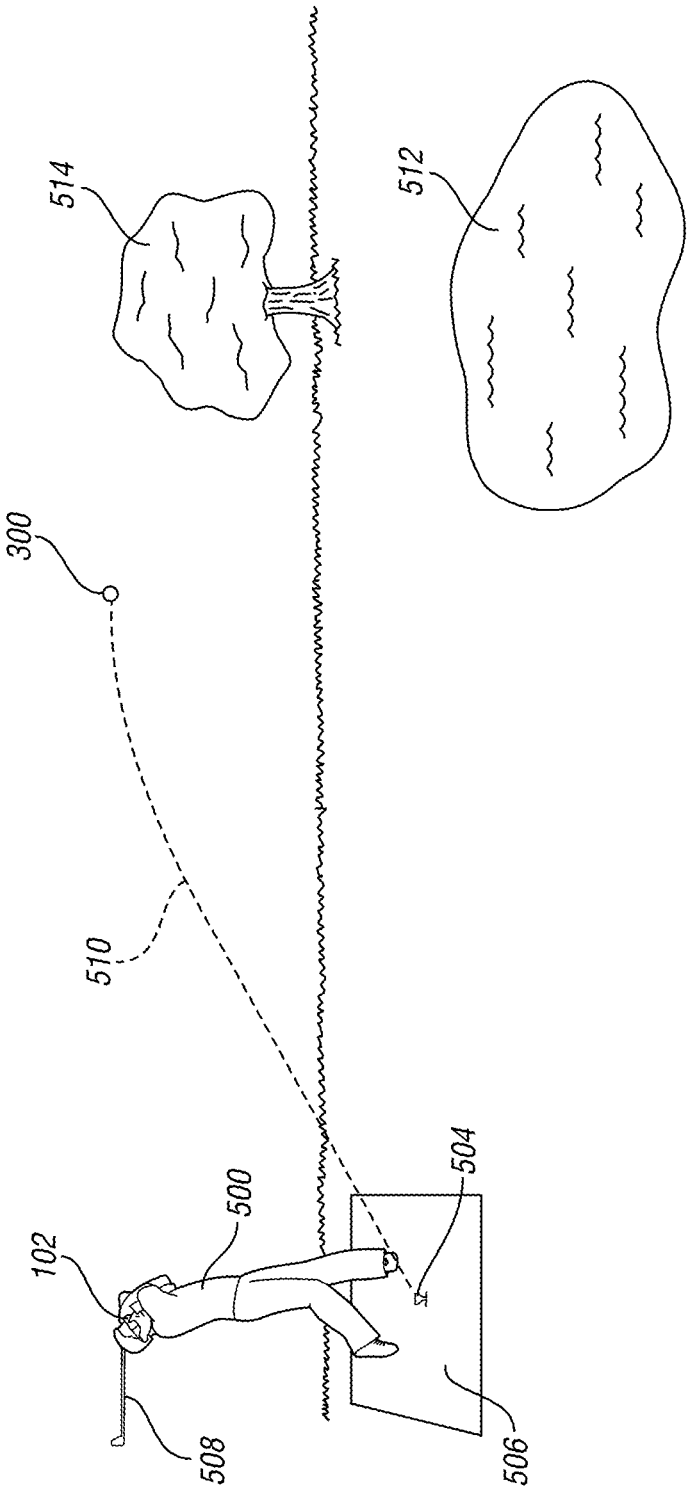


FIG. 5

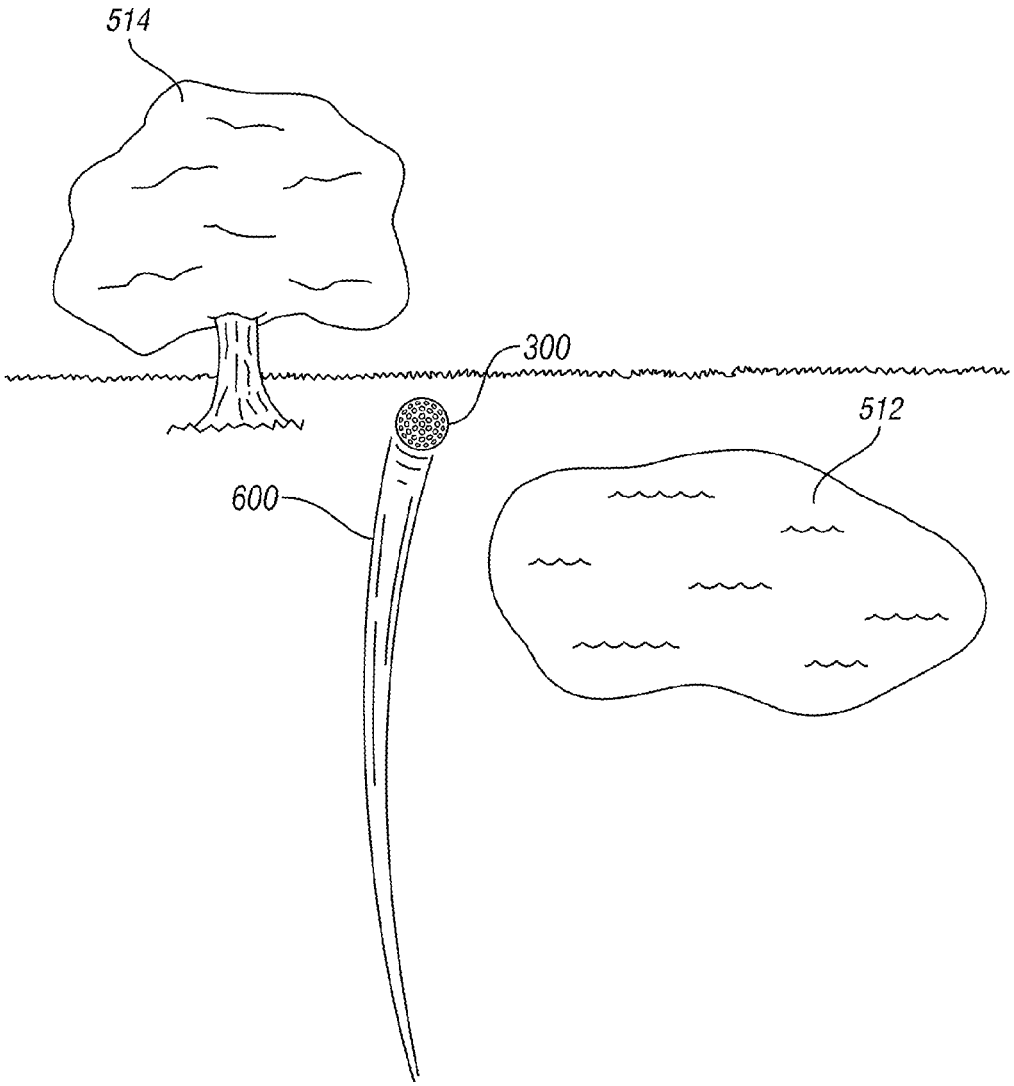


FIG. 6

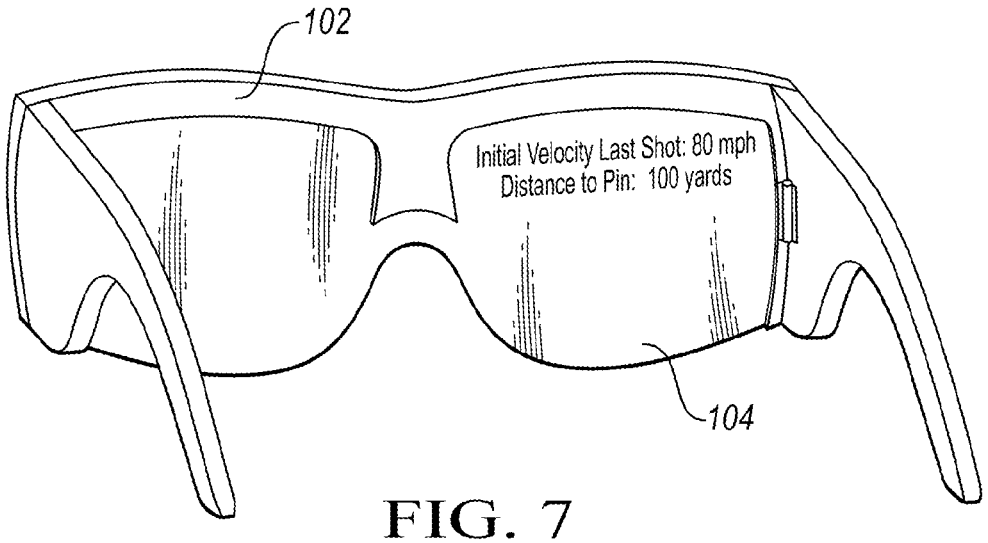

102
Initial Velocity Last Shot: 80 mph
Distance to Pin: 100 yards
104

FIG. 7

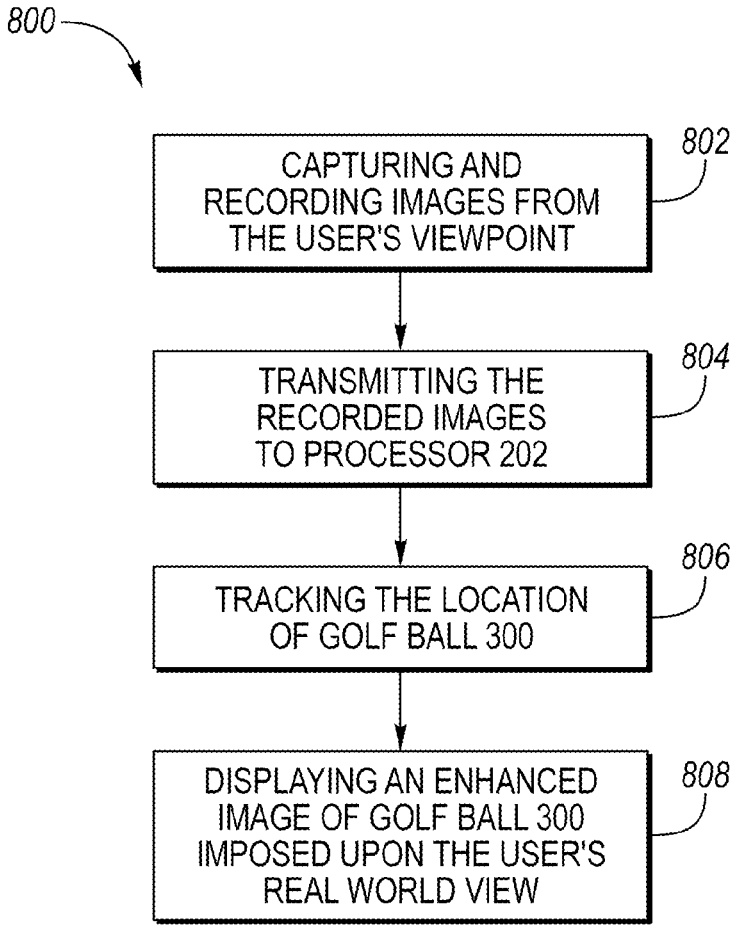

800
CAPTURING AND RECORDING IMAGES FROM THE USER'S VIEWPOINT
802
TRANSMITTING THE RECORDED IMAGES TO PROCESSOR 202
804
TRACKING THE LOCATION OF GOLF BALL 300
806
DISPLAYING AN ENHANCED IMAGE OF GOLF BALL 300 IMPOSED UPON THE USER'S REAL WORLD VIEW
808

FIG. 8

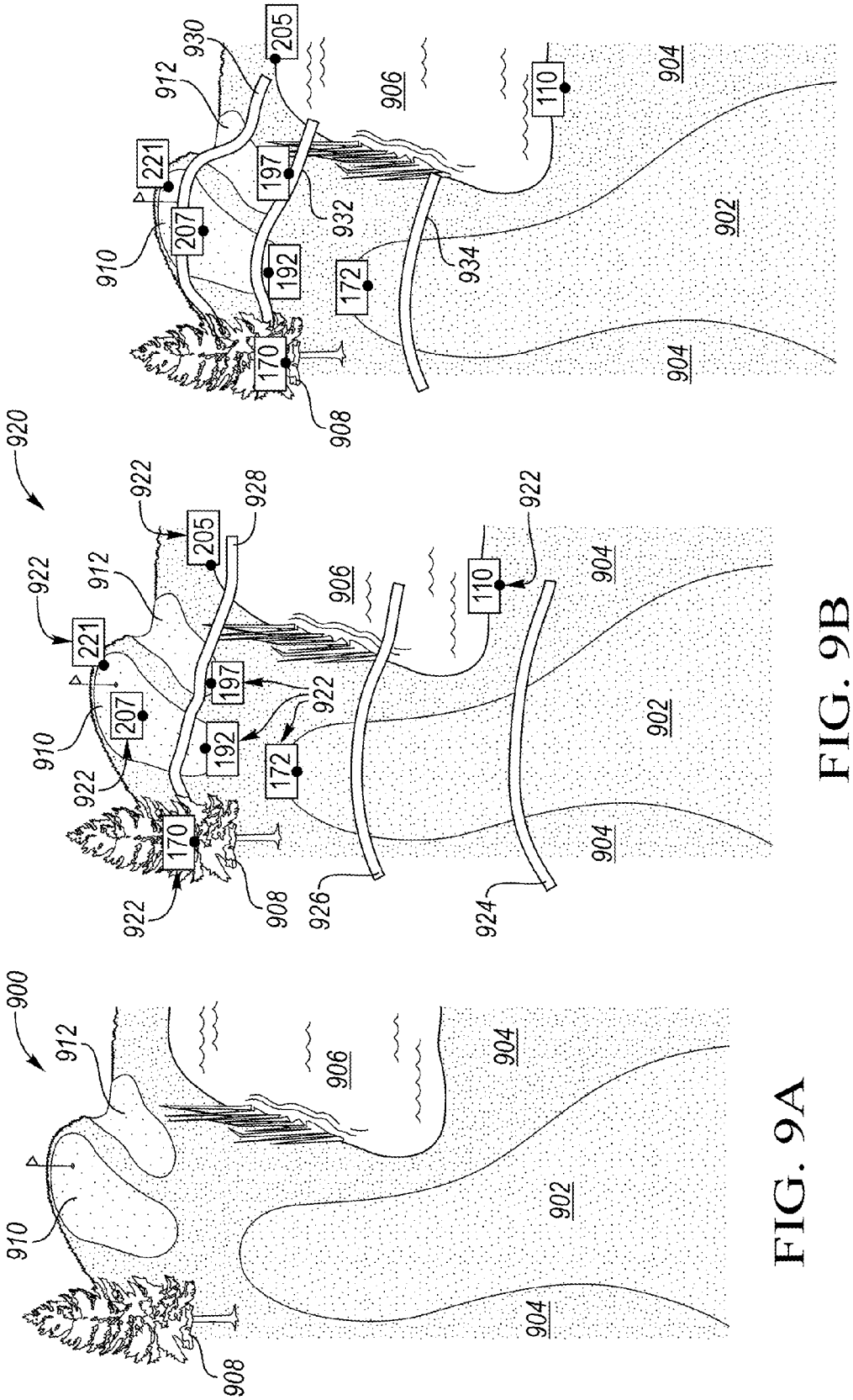


FIG. 9A

FIG. 9B

FIG. 9C

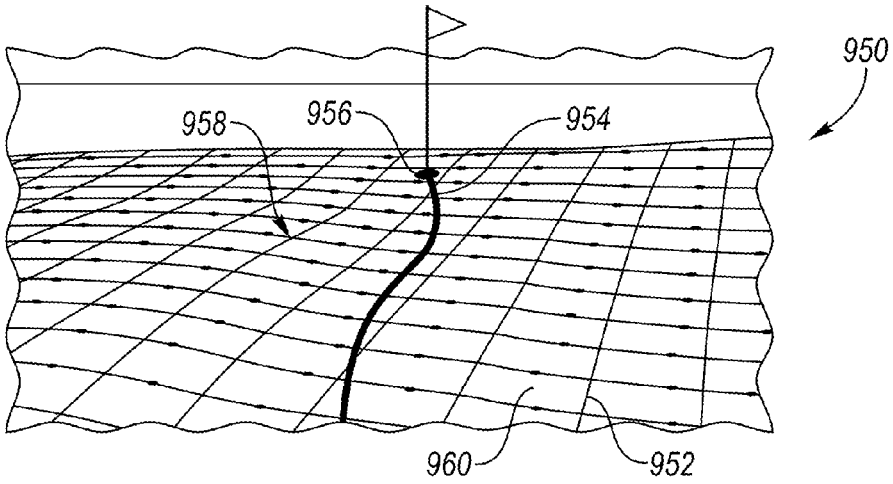

950
958
956
954
960
952

FIG. 10

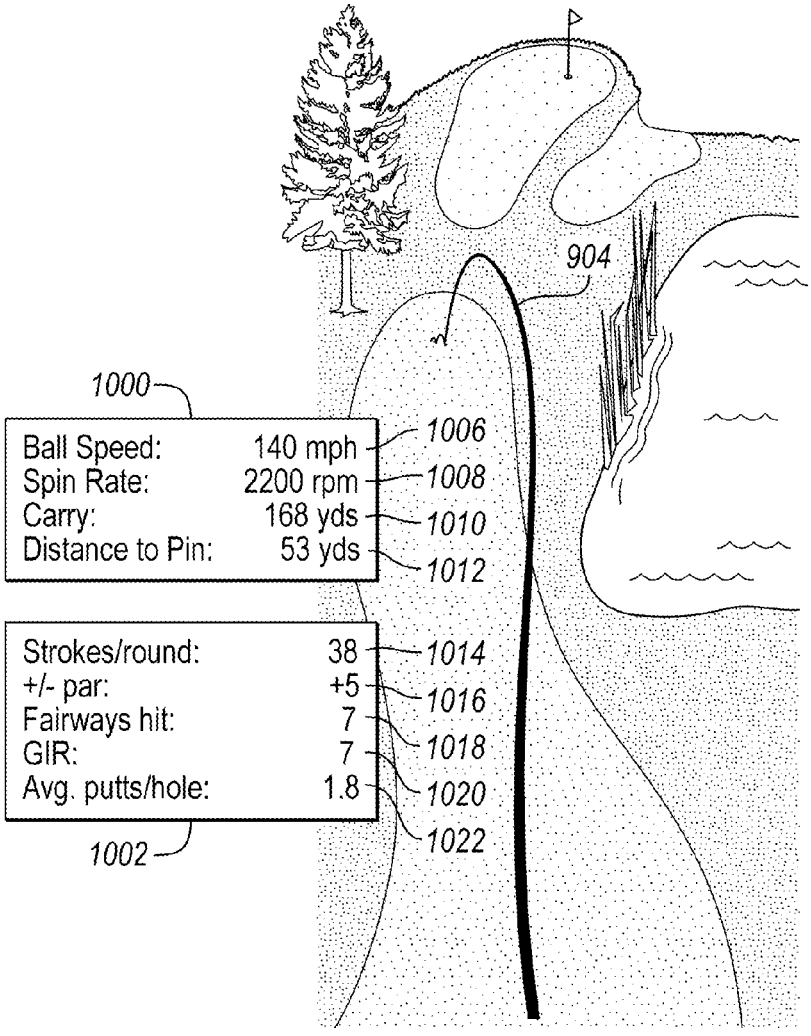

904
1000
Ball Speed: 140 mph
Spin Rate: 2200 rpm
Carry: 168 yds
Distance to Pin: 53 yds
1006
1008
1010
1012
Strokes/round: 38
+/- par: +5
Fairways hit: 7
GIR: 7
Avg. putts/hole: 1.8
1014
1016
1018
1020
1022
1002

FIG. 11

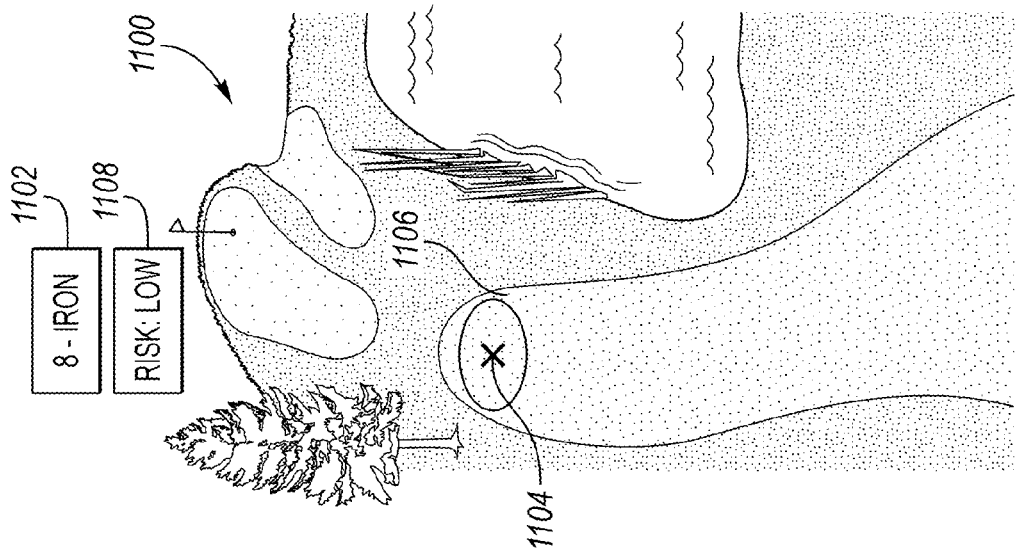

1100
1102
8 - IRON
1108
RISK: LOW
1106
1104

FIG. 13

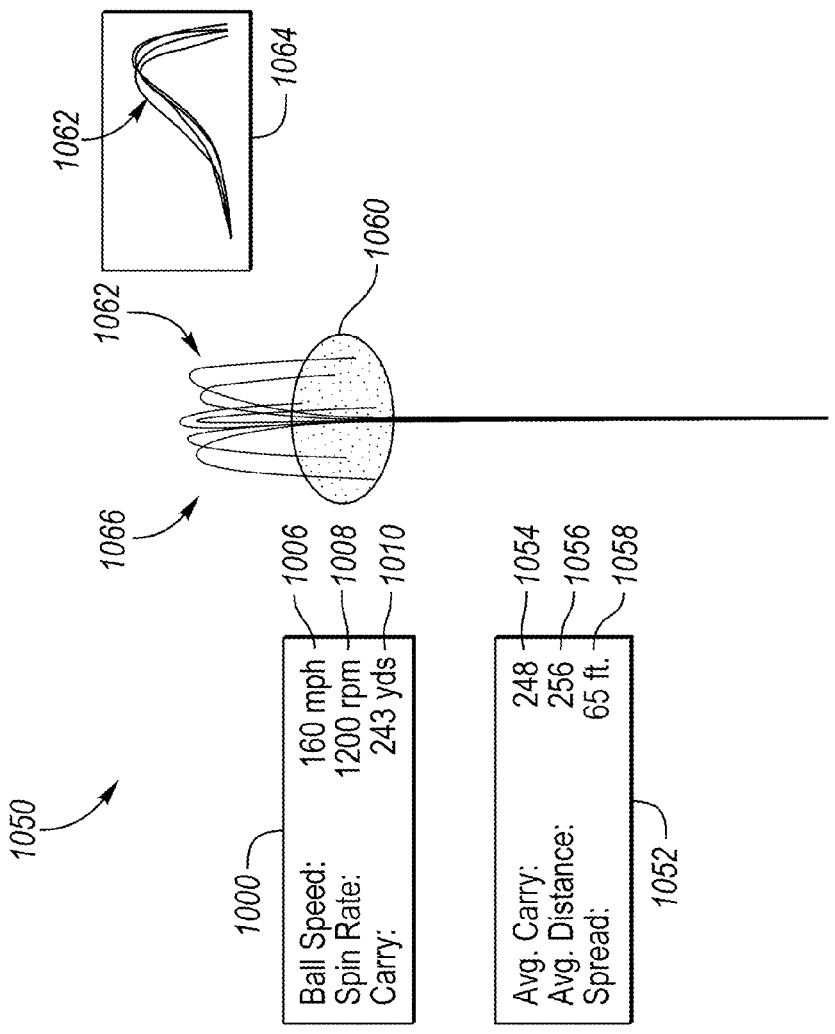

1050
1000
Ball Speed: 160 mph
Spin Rate: 1200 rpm
Carry: 243 yds
1006
1008
1010
Avg. Carry: 248
Avg. Distance: 256
Spread: 65 ft.
1054
1056
1058
1052
1062
1064
1060
1062
1066

FIG. 12

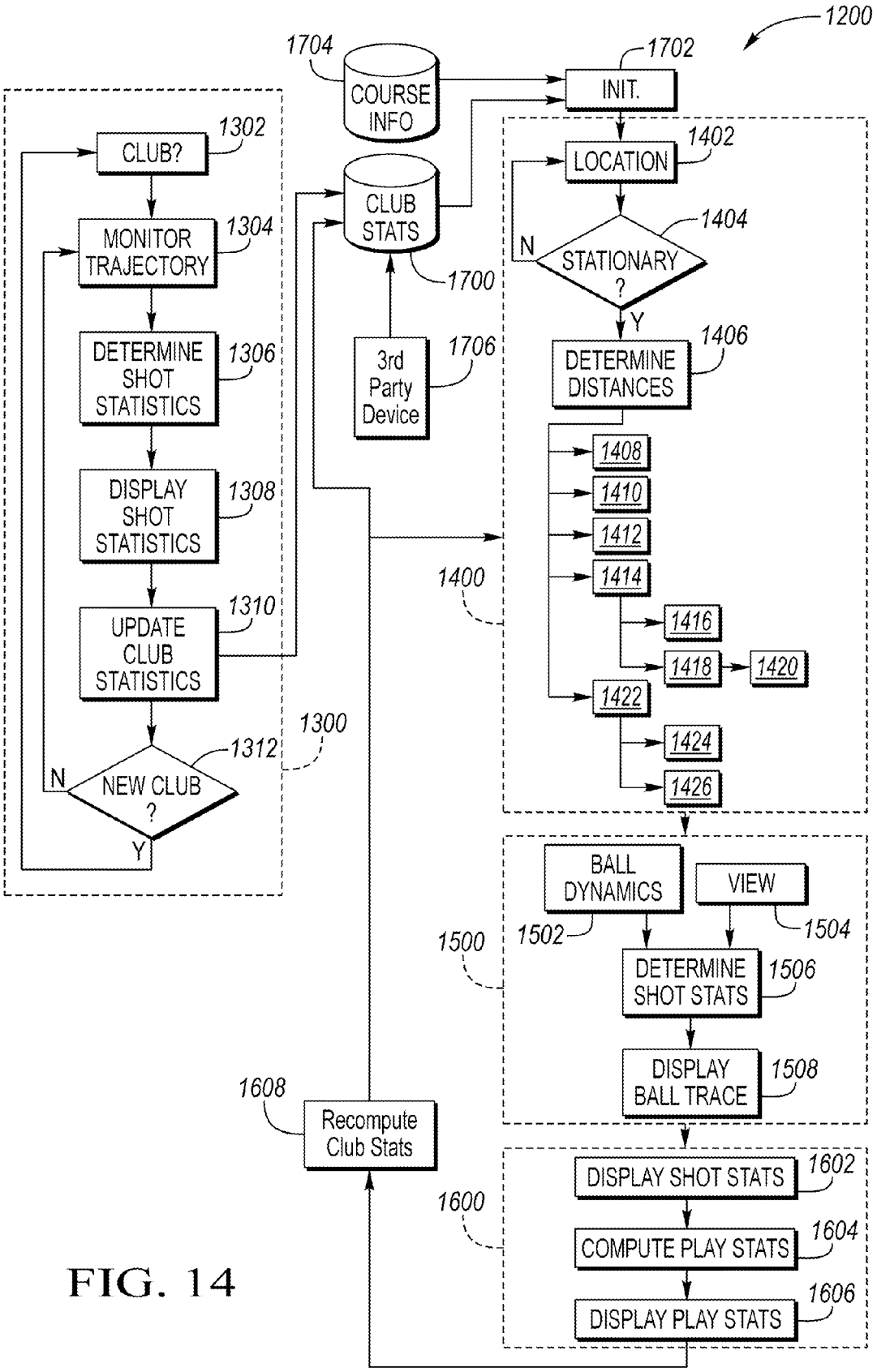

1200
1704
COURSE INFO
1702
INIT.
1302
CLUB?
1402
LOCATION
CLUB STATS
1404
N
STATIONARY ?
1304
MONITOR TRAJECTORY
1700
Y
1706
3rd Party Device
1406
DETERMINE DISTANCES
1306
DETERMINE SHOT STATISTICS
1408
1410
1412
1308
DISPLAY SHOT STATISTICS
1414
1400
1310
UPDATE CLUB STATISTICS
1416
1418
1420
1422
1424
1426
1300
1312
N
NEW CLUB ?
Y
BALL DYNAMICS
VIEW
1502
1504
1500
DETERMINE SHOT STATS
1506
DISPLAY BALL TRACE
1508
1608
Recompute Club Stats
DISPLAY SHOT STATS
1602
1600
COMPUTE PLAY STATS
1604
DISPLAY PLAY STATS
1606

FIG. 14

GOLF AID INCLUDING HEADS UP DISPLAY

TECHNICAL FIELD

The present invention relates generally to a golf aid for conveying golf-related information via a heads up display.

BACKGROUND

The game of golf is an increasingly popular sport at both amateur and professional levels. Both amateur and professional golfers spend sizeable amounts of time developing the muscle memory and fine motor skills necessary to improve their game. Golfers try to improve their game by analyzing launch and trajectory information while playing golf. Also, a better understanding of club hitting characteristics may allow a golfer to more properly select a club during a round of golf.

SUMMARY

A golf aid having a practice mode for use while hitting a plurality of golf balls with a golf club includes a golf ball tracking system, a heads up display configured to be worn on the user's head and display an image within a field of view of the user, and a processor in communication with the golf ball tracking system and the heads up display.

The a golf ball tracking system is configured to track a plurality of golf ball trajectories, each one of the plurality of trajectories corresponding to a respective one of the plurality of golf balls being hit by the golf club.

The processor is configured to compute one or more shot statistics for each one of the plurality of trajectories and display the one or more computed shot statistics within the field of view of the user. The one or more shot statistics include at least one of an initial ball speed, a spin rate, a total distance, and a carry distance. The processor is further configured to display a plurality of traces within the field of view of the user via the heads up display. Each one of the plurality of traces corresponds to a respective one of the plurality of trajectories. In one configuration, the processor may further be configured to compute one or more club statistics for a second golf club from a second plurality of trajectories.

In another embodiment, the processor may be operable to execute instructions stored on a non-transitory, computer readable medium to assist a user by displaying one or more golf-related statistics. When executed, the stored instructions cause the processor to perform steps that include receiving an indication of a tracked flight of a plurality of golf ball trajectories from a sensor, each one of the plurality of trajectories corresponding to a respective one of a plurality of golf balls being hit by a golf club. The processor may then compute one or more shot statistics for each one of the plurality of trajectories. The one or more shot statistics include at least one of an initial ball speed, a spin rate, a total distance, and a carry distance. Following the computation, the processor may display the one or more shot statistics within the field of view of the user via the heads up display. Additionally, the processor may display a plurality of traces within the field of view of the user via the heads up display, where each one of the plurality of traces corresponds to a respective one of the plurality of trajectories.

The above features and advantages and other features and advantages of the present invention are readily apparent from the following detailed description of the best modes for carrying out the invention when taken in connection with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. **1** is a schematic partially perspective view of embodiment of the disclosed system.

FIG. **2** is a schematic diagram of the embodiment of FIG. **1**.

FIG. **3** is a top view of a golf ball provided with communication components.

FIG. **4** is a perspective partial cross sectional view of the golf ball of FIG. **3**.

FIG. **5** is a schematic side perspective view of a golfer wearing the system shown in FIGS. **1-2** and hitting the golf ball of FIGS. **3-4**.

FIG. **6** is an schematic enhanced image of the golf ball imposed upon the golfer's real world view.

FIG. **7** is a schematic perspective view of information displayed on the eyeglasses of FIGS. **1-2**.

FIG. **8** is a schematic flow chart of a method of displaying an enhanced image of the golf ball imposed upon the golfer's real world view according to an embodiment.

FIG. **9**A is a schematic perspective view of a golfer's real world view of a golf hole.

FIG. **9**B is a schematic enhanced image of distance markers imposed upon the golfer's real world view of FIG. **9**A.

FIG. **9**C is a schematic enhanced image of distance markers imposed upon the golfer's real world view of FIG. **9**A.

FIG. **10** is a schematic enhanced image of putting aid imposed upon a golfer's real world view.

FIG. **11** is a schematic enhanced image of shot statistics and play statistics imposed upon the golfer's real world view of FIG. **9**A.

FIG. **12** is a schematic enhanced image of a plurality of ball traces and both shot statistics and club statistics imposed upon a golfer's real world view.

FIG. **13** is a schematic enhanced image of an optimized club selection and target imposed upon the golfer's real world view of FIG. **9**A.

FIG. **14** is a schematic flow chart of a method that may be performed by a processor to provide enhanced imagery within a practice mode, before a shot, during a shot, and after a shot.

DETAILED DESCRIPTION

A system for tracking a golf ball is disclosed. The system may track the trajectory of a golf ball and display an enhanced image of the golf ball on a display such that the enhanced image is imposed upon a user's real world view. Displaying an enhanced image of the golf ball may help a user view the trajectory of the golf ball and find the golf ball after the golf ball lands. In some embodiments, the system may display an enhanced image of the golf ball on a heads-up display configured to be worn on a person's head. For example, the heads-up display may include a pair of eyeglasses having a lens. By displaying an enhanced image of the golf ball on the lens, the user may view the enhanced image while remaining hands-free. The enhanced image may include at least a portion of the trajectory of the golf ball. Thus, the enhanced image may facilitate tracking the trajectory of the golf ball, which may help the user to compare the golf ball's trajectory with an ideal trajectory. The enhanced image may also help the user see where the golf ball lands, which may help a user find the golf ball. The system may display other information, such as launch and flight information about the ball, on the heads-up display.

FIGS. **1** and **2** illustrate an embodiment of a system **100** for tracking a golf ball. System **100** may include a display device configured to be worn on a person's head. As shown in FIG.

1, the display device may include a pair of eyeglasses **102**. For example, the display device may include any of the head mounted displays described in U.S. Pat. No. 7,595,933, entitled Head Mounted Display System, issued to Tang on Sep. 29, 2009, the disclosure of which is hereby incorporated by reference in its entirety. A display system **208** may be associated with eyeglasses **102** to display images to the user. System **100** may include a golf ball tracking system **200** to track the location of a golf ball. System **100** may include a user tracking system **206** to track the location of the user to help navigate and/or determine distances between the user and landmarks, such as, for example, trees, sandtraps, doglegs, natural hazards (e.g., water, tall grass, bluffs etc), front/middle/back portions of a green, layup areas, and/or the next pin on the golf course. System **100** may include a camera **204** configured to capture and record images of the user's real world view to determine where to display enhanced images to the user such that the enhanced images are imposed upon the user's real world view. System **100** may include an interface **114** to enable a user to communicate with system **100**. System **100** may include at least one processor **202** configured to control camera **204**, golf ball tracking system **200**, user tracking system **206**, and/or display system **208**. In some embodiments, processor **202** may be coupled to camera **204**, golf ball tracking system **200**, user tracking system **206**, and/or display system **208**. In some embodiments, processor **202** may be configured to communicate with camera **204**, golf ball tracking system **200**, user tracking system **206**, and/or display system **208**. In some embodiments, system **100** may include more than one processor. For example, in some embodiments, a separate processor may be included for each component of system **100**.

In this manner, the processor **202** may be embodied as one or multiple digital computers, data processing devices, and/or digital signal processors (DSPs), which may have one or more microcontrollers or central processing units (CPUs), read only memory (ROM), random access memory (RAM), electrically-erasable programmable read only memory (EEPROM), high-speed clock, analog-to-digital (A/D) circuitry, digital-to-analog (D/A) circuitry, input/output (I/O) circuitry, and/or signal conditioning and buffering electronics. The processor **202** may further be associated with computer readable non-transitory memory having stored thereon instructions that cause the processor **202** to provide an informational display to a user via the display system **208**

While the embodiment of FIG. **1** includes eyeglasses **102**, other embodiments may include other types of display devices configured to be mounted on a person's head. For example, system **100** may include a visor, helmet, or goggles. The type of display device may be selected based on a variety of factors. For example, the type of display device may be selected based on the type of environment system **100** is meant to be used in. Components of system **100** may be mounted to eyeglasses **102**. Eyeglasses **102** may be hollow such that components of system **100** may be housed within eyeglasses **102**. In some embodiments, eyeglasses **102** may include a removable cover **118** for allowing access to any components mounted within eyeglasses **102**. Eyeglasses **102** may include one or more lenses. FIG. **1** shows eyeglasses **102** with a single lens **104**. In some embodiments, lens **104** may include a partially reflective mirror. The partially reflective mirror may allow the real world to be seen through the reflected surface such that a transparent image may be imposed upon a real world view.

Display system **208** may be mounted on and housed within eyeglasses **102**. In some embodiments, display system **208** may include optical components, projecting components, imaging devices, power sources, and/or light sources. For example, display system **208** may include the components as described in U.S. Pat. No. 7,595,933. In some embodiments, display system **208** may include components that display images. For example, display system **208** may include a display element, such as a flat panel display or a liquid crystal display, as described in U.S. Pat. No. 7,595,933. In some embodiments, lens **104** may include a lens system that relays images to a user's eye from a display element.

User tracking system **206** may include one or more user location sensors **120**. User location sensor **120** may sense the location of the user. User location sensor **120** may be mounted on and housed within eyeglasses **102**. User location sensor **120** may be positioned in any suitable position. The type of user location sensor may include any suitable type of sensor. For example, user location sensor **120** may include a global positioning system receiver. The location, number, and type of user location sensor(s) may be selected based on a number of factors. For example, the type of user location sensor(s) may be selected based on the other types of components included in system **100**. In some embodiments, processor **202** may be configured to communicate with user location sensor **120** to determine the location of the user on a golf course and to determine the distance between the user and a landmark on the golf course. For example, in some embodiments, processor **202** may be configured to communicate with user location sensor **120** to determine the distance between the user and the next pin on the course. Such information would help a user find his yardages during a round of golf.

Golf ball tracking system **200** may include one or more golf ball sensors. The golf ball sensor may be configured to detect the golf ball. The golf ball sensor may be mounted on or housed within eyeglasses **102**. For example, as shown in FIG. **1**, a golf ball sensor **110** may be mounted such that golf ball sensor **110** is exposed through an opening **112** in eyeglasses **102**. FIG. **1** shows golf ball sensor **110** as being mounted such that it will be positioned above the user's left eye when a user wears eyeglasses **102**. In other embodiments, golf ball sensor **110** may be positioned in any suitable position. The location and number of golf ball sensors **110** may be selected based on a number of factors. For example, the location of the golf ball sensor **110** may be selected based on the positioning of other components and/or the sensitivity of the golf ball sensor **110**.

In some embodiments, the golf ball sensor **110** may include a reflective sensor capable of detecting the location of a golf ball without any communication components being provided within the golf ball. For example, the golf ball sensor **110** may include radar, LIDAR, optical, and/or sonar sensors. In some embodiments, the golf ball tracking system **200** may include communication components provided inside and/or on the golf ball. Such golf ball tracking systems may include a golf ball sensor **110** capable of detecting the location of a golf ball by detecting a tracking component provided within the golf ball. For example, the golf ball tracking system **200** may include a radio-frequency identification system, a BLUETOOTH technology system, an infrared system, and/or global positioning system receiver.

In some embodiments, camera **204** may act as the golf ball tracking system **200**. Camera **204** may find the contrast difference between the golf ball and the background of the ball as the golf ball travels. For example, camera **204** may find the contrast difference between the golf ball and the sky as the golf ball flies through the air.

In some embodiments, the golf ball tracking system **200** may include a special coating on the golf ball. Such golf ball tracking systems **200** may include a golf ball sensor **110** capable of detecting the location of a golf ball by detecting the

special coating provided on the golf ball. The special coating may include an ultraviolet sensitive paint and the golf ball sensor **110** may include a camera **204** configured to capture images illuminated by ultraviolet light only. For example, a UV transmitting, visible light blocking filter may be included over the camera lens so that only ultraviolet passes through the filter and all visible light is absorbed by the filter.

In some embodiments, the golf ball sensor **110** and the user location sensor **120** may include the same type of sensor. For example, the golf ball sensor **110** and the user location sensor **120** may both include an infrared system. Embodiments of golf ball tracking systems **200** are described in more detail below.

Camera **204** may capture and record images from the user's viewpoint. The camera **204** may include any suitable type of camera. The type of camera may be selected based on a variety of factors. For example, the type of camera may be selected based on the type of display included in the system or the type of golf ball tracking system **200** used in the system. The camera **204** may be mounted on or inside eyeglasses **102**. For example, as shown in FIG. **1**, a camera **204** may be mounted inside eyeglasses **102** with a camera lens **106** exposed through an opening **108** in eyeglasses **102**. FIG. **1** shows camera lens **106** as being mounted so that it will be positioned above the user's right eye when a user wears eyeglasses **102**. In other embodiments, the camera **204** may be positioned in any other suitable position. The location of the camera **204** may be selected based on a number of factors. For example, the location of the camera **204** may be selected to provide the camera lens **106** in a position close to the user's eye so that the view from the camera **204** is similar to the view from the user's eye.

In some embodiments, processor **202** may be configured to process information relayed to and from the golf ball sensor **110** and/or the communication component provided with the golf ball. Processor **202** may use this information to determine the location of the golf ball. In some embodiments, the processor may also be configured to control display system **208**. As a result, the processor **202** may control the images shown by the display. In some embodiments, processor **202** may be configured to process information relayed to and from user location sensor **120**. The processor **202** may use this information to determine the location of the user. In some embodiments, the processor **202** may determine the distance between the user and a landmark, such as the pin or a restroom. In some embodiments, processor **202** may be configured to process information relayed to processor **202** from camera **204**. Processor **202** may use this information to display images captured and recorded by the camera to the user. Processor **202** may be configured to display enhanced images to the user.

In some embodiments, the system may include an interface **114** configured to communicate with components of the system. In some embodiments, the interface may be in communication with golf ball tracking system **200**, camera **204**, and/or eyeglasses **102** either directly or through processor **202**. Interface **114** may be in communication with processor **202**, golf ball tracking system **200**, camera **204**, and/or eyeglasses **102** either wirelessly or by wire. For example, FIG. **1** shows wire **116** extending through an opening **122** in eyeglasses **102**. Wire **116** may couple interface **114** to processor **202**. Interface **114** may provide the user with a way to control system **100**. In some embodiments, interface **114** may have an interface display. Such an interface display may show information about control settings and commands for system **100**. In some embodiments, interface **114** may have inputs for providing data and control signals to system **100**. For example, interface **114** may have buttons. In some embodiments, system **100** may include a touch screen that provides both an interface display and an input. In some embodiments, a user may wear eyeglasses **102** and put interface **114** in his pocket during use.

As discussed above, golf ball tracking system **200** may include a golf ball provided with communication components that are configured to communicate with a golf ball sensor **110**. FIGS. **3** and **4** show a golf ball **300** that may be provided with communication components. Golf ball **300** may include any suitable type of golf ball. For example, in some embodiments, golf ball **300** may be a one-piece golf ball. In other embodiments, golf ball **300** may be a multi-piece golf ball, such as a 2-piece or 3-piece golf ball. Golf ball **300** may have an outer surface including dimples **302**. Golf ball **300** may be provided with communication components including emitting diodes **304** and a microchip **400**. For example, the communication components may include those described in U.S. Pat. No. 6,634,959, entitled Golf Ball Locator, issued to Kuesters on Oct. 21, 2003, the disclosure of which is hereby incorporated by reference in its entirety, and as described in U.S. Pat. No. 5,564,698, entitled Electromagnetic Transmitting Hockey Puck, issued to Honey et al. on Oct. 15, 1996, the disclosure of which is hereby incorporated by reference in its entirety. Emitting diodes **304** may be disposed on the outer surface of golf ball **300**. FIG. **4** shows a cross-sectional view of golf ball **300**. As shown in FIG. **4**, microchip **400** may be disposed inside golf ball **300**. Emitting diodes **304** may be connected to microchip **400** by wires **402**. In some embodiments, microchip **400** may be configured to power and control emitting diodes **304**. In some embodiments, microchip **400** may be configured to communicate with processor **202**. For example, microchip **400** may be configured to communicate with processor **202** via wireless signals. In some embodiments, microchip **400** may include a power source, timing circuits, on/off switches, a pulsing circuit, and/or shock sensors to control the powering of emitting diodes **304**. In such embodiments, the shock sensors may be configured to detect movement of golf ball **300**. Accordingly, movement of golf ball **300** may trigger the on/off switch to power emitting diodes **304**. To conserve power, timing circuits may be configured to control how long emitting diodes **304** are powered. Thus, shock sensors may detect when a golf club strikes golf ball **300**, which may trigger the on/off switch to power emitting diodes **304** while golf ball **300** is in flight. After a predetermined amount of time, the timing circuits may trigger the on/off switch to shut off power to emitting diodes **304**.

In embodiments in which golf ball **300** includes emitting diodes **304**, golf ball sensor **110** may be configured to detect signals from emitting diodes **304**. For example, emitting diodes **304** may include infrared emitting diodes and golf ball sensor **110** may include an infrared receiver. Golf ball sensor **110** may transmit this data to processor **202**. Processor **202** may be configured to use this data to determine the location of emitting diodes **304**, and thus, the location of golf ball **300**. In some embodiments, in place of or in addition to golf ball sensor **110**, camera **204** may be configured to detect emissions from emitting diodes **304**. In some embodiments, in place of or in addition to golf ball sensor **110**, multiple golf ball sensors may be provided in the location in which the golf ball is to be tracked. For example, multiple golf ball sensors may be provided in various positions on a golf course. In such embodiments, the position of the golf ball sensors may be known and the golf ball sensors may be used to determine the location of the golf ball by detecting emissions from emitting diodes **304**.

FIG. **5** illustrates a user **500** wearing eyeglasses **102** while using a golf club **508** to hit a golf ball **300** off of a tee **504** in a tee box **506** along path **510**. FIG. **6** shows the user's view after he hits golf ball **300**. Eyeglasses **102** provide an enhanced image of golf ball **300** imposed upon the user's real world view such that the enhanced image's position matches the position of golf ball **300**. In FIG. **6**, the user's real world view through lens **104** includes golf ball **300**, a tree **514**, and a pond **512** disposed within user's line of sight. The enhanced image adds a comet tail **600** to golf ball **300** as golf ball **300** flies through the air toward tree **514** and pond **512**. Comet tail **600** may lag behind golf ball **300** such that comet tail **600** stays visible after golf ball **300** lands. Comet tail **600** may represent at least a portion of the trajectory of golf ball **300**. In some embodiments, comet tail **600** may represent the entire trajectory of golf ball **300**. As a result, user **500** may see the entire trajectory of golf ball **300** at least temporarily after golf ball **300** lands.

FIG. **8** shows a method **800** of displaying an enhanced image of the golf ball imposed upon the golfer's real world view according to an embodiment. The steps of method **800** may be performed in any order. Step **802** may include capturing and recording images from the user's viewpoint. Step **804** may include transmitting the recorded images to processor **202**. Camera **204** may perform steps **802** and **804**. Step **806** may include tracking the location of golf ball **300**. Golf ball tracking system **200** and/or processor **202** may perform step **806**. For example, in the embodiment discussed above with reference to FIGS. **3** and **4**, hitting golf ball **300** may trigger shock sensors. As a result, on/off switches may cause microchip **400** to power emitting diodes **304**, which may cause emitting diodes **304** to pulse. Golf ball sensor **110** may detect the pulses and transmit data to processor **202**. Processor **202** may use the transmitted data to determine the location of emitting diodes **304**, and thus, the location of golf ball **300**.

Step **808** may include displaying an enhanced image of golf ball **300** upon the user's real world view. In some embodiments, processor **202** may use the location of golf ball **300** and the images recorded by camera **204** to make display system **208** display an enhanced image of golf ball **300** to user **500**. The enhanced image may be displayed such that the enhanced image overlays the user's real world view. In some embodiments, the enhanced image may be transparent. In some embodiments, the enhanced image may be stereoscopic. In some embodiments, the enhanced image may be bigger and/or brighter than the recorded image. For example, the enhanced image may appear to be glowing. The enhanced image may be selected to make golf ball **300** and the trajectory of golf ball **300** stand out more to the user while allowing user to still see a real world view. As shown in FIG. **6**, the enhanced image may include comet tail **600** trailing behind golf ball **300**. Comet tail **600** may show the trajectory of golf ball **300** such that user **500** can compare the trajectory of golf ball **300** to an ideal trajectory. In some embodiments, display system **208** may display an ideal trajectory such that the trajectory of golf ball **300** may be compared with the ideal trajectory.

In some embodiments, processor **202** may use the location of golf ball **300** at various times to determine launch information and/or flight information about golf ball **300**. In some embodiments, to determine launch information and/or flight information about golf ball **300**, system **100** may use methods and components described in U.S. Patent Application Publication 2007/0021226, entitled Method of and Apparatus for Tracking Objects in Flight Such as Golf Balls and the Like, applied for by Tyroler and published on Jan. 25, 2007, the disclosure of which is hereby incorporated by reference in its entirety. In some embodiments, to determine launch information and/or flight information about golf ball **300**, system **100** may use methods and components described in U.S. Patent Application Publication 2005/0233815, entitled Method of Determining a Flight Trajectory and Extracting Flight Data for a Trackable Golf Ball, applied for by McCreary et al. and published on Oct. 20, 2005, the disclosure of which is hereby incorporated by reference in its entirety. In some embodiments, to determine launch information and/or flight information about golf ball **300**, system **100** may use methods and components described in U.S. Patent Application Publication 2010/0151955, entitled Global Positioning System Use for Golf Ball Tracking, applied for by Holden and published on Jun. 17, 2010, the disclosure of which is hereby incorporated by reference in its entirety. To determine launch information and/or flight information about golf ball **300**, system **100** may use methods and components described in U.S. Patent Application Publication 2008/0254916, entitled Method of Providing Golf Contents in Mobile Terminal, applied for by Kim et al. and published on Oct. 16, 2008, the disclosure of which is hereby incorporated by reference in its entirety. FIG. **7** shows how information may be displayed to the user. For example, launch information, such as initial velocity, and the distance to the pin may be displayed on lens **104**. In another example, lens **104** may display the ball spin rate and/or launch angle. By displaying information to user **500** on eyeglasses **102**, user **500** may reference this information without having to pull out a device or without having do anything other than look in front of his eye. Accordingly, the user may quickly and easily reference information without having to distract from other activities.

In some embodiments, system **100** may include a separate launch monitor configured to monitor and record data related to the golf ball, golf club, and/or golfer. For example, system **100** may include the launch monitor described in U.S. patent application Ser. No. 13/307,789, entitled Method and Apparatus for Determining an Angle of Attack from Multiple Ball Hitting, applied for by Ishii et al. and filed on Nov. 30, 2011, the disclosure of which is hereby incorporated by reference in its entirety. The separate launch monitor may be in communication with processor **202**.

User tracking system **206** may determine the location of user **500**. For example, in embodiments in which global positioning system receiver **120** is included in eyeglasses **102**, global positioning system receiver **120** may determine the location of user and transmit the location of the user to processor **202**. Processor **202** may be configured to know the locations of various landmarks on a golf course. Processor **202** may be configured to determine the distance between the location of the user and the various landmarks on the golf course. For example, processor **202** may be configured to determine the distance between user **500** and the next pin on the golf course. Processor **202** may be configured to display this distance to user **500**, as shown in FIG. **7**. In some embodiments, the user may be a golfer wearing eyeglasses **102**. In some embodiments, the user may be a caddy wearing eyeglasses **102** and watching a golfer. The caddy may use the system to help the golfer choose clubs, adjust his swing, and find golf balls. In some embodiments, the user may be a spectator wearing the eyeglasses and watching a golfer.

In some embodiments, system **100** may display an image of golf ball **300** and/or an image of user **500** on a representation of the golf course. Display system **208** may display these images to user **500** on eyeglasses **102** to help user **500** navigate and/or locate golf ball **300**. To display the images, system **100** may use the methods and components described in U.S. Patent Application Publication 2007/0021226, U.S. Patent

Application Publication 2005/0233815, U.S. Patent Application Publication 2010/0151955, and/or U.S. Patent Application Publication 2008/0254916.

FIG. **9**A schematically illustrates a (non-enhanced) view **900** that a user may have while standing in a fairway **902** of a golf course. In this example, the user may see the fairway **902**, the rough **904**, a lake **906**, a prominent tree **908**, the green **910**, and a sand bunker **912** next to the green **910**. FIG. **9**B schematically illustrates an enhanced view **920** of the scene provided in FIG. **9**A, which may be available, for example, through the eyeglasses **102** described above.

Using the user's present location as determined by the user tracking system **206**, together with known locations of the various objects, the processor **202** may compute a plurality of relative distances and display them to the user via the eyeglasses **102**. In addition to computing relative distances, such as by differencing GPS location coordinates, the system **100** may utilize miniaturized optical, radar, or LIDAR sensors provided on the eyeglasses **102** (e.g., sensors that may be used with the golf ball tracking system **200**) to determine the distance between the user and the one or more respective objects. This reading may then either be used instead of the GPS measurement, or may be fused with and/or used to refine the GPS measurement.

Once the distances to the various objects are computed, numerical representations **922** of the distances may be displayed within the user's view either coincident with the object or directly adjacent to the object. In this example, distances are computed and displayed for the nearest shoreline of the lake **906**, the farthest shoreline of the lake **906**, the prominent tree **908**, the front, middle, and back of the green **910**, and the center of the sand bunker **912**. In one configuration, the marked objects (i.e., those objects to which distances are provided) may be pre-determined by the user, a different user, or a golf professional familiar with the course. Once the ball is struck, these distances may clear from the view, and other views (such as a ball trace) may be displayed.

In addition to merely computing and displaying distances to objects, the system **100** may be configured to display visual imagery in a manner that makes the imagery appear to the user as if it is resting on or slightly above the ground. For example, in FIG. **9**B, the system **100** may project distance lines **924**, **926**, **928** across the fairway to indicate 100 yds, 150 yds, and 200 yds (respectively). It should be appreciated that these yardages are arbitrary, and may be customized by the user. In one configuration, such as schematically illustrated in FIG. **9**C, the distance lines may coincide with average or typical hitting distances that are typical for the user following a full-powered swing. For example, the system **100** may project lines **930**, **932**, **934** that are representative of a full power swing from a 4 iron, a 5 iron, and an 8 iron (respectively). In one configuration, the club-based distance lines **930**, **932**, **934** that are displayed may dynamically adjust based on the determined yardages to the various objects and/or safe landing zones. In this manner, the system **100** may aid the user in determining the proper club to use for a given shot.

In one configuration, the club-based distance lines **930**, **932**, **934** may be based on hitting data that the user may manually enter into the system **100** according to known tendencies. In another configuration, the distance lines **930**, **932**, **934** may be based on actual shot data that is recorded by the system **100** and averaged for each club. This statistical averaging may, for example, use filtering techniques to prevent errant shots or outlier distances from affecting the mean-max club distances. To facilitate the automatic data-gathering, the system **100** must understand which club was used for each resulting shot. This may occur through, for example, user input, visual recognition of the club when the club is drawn from the bag (e.g., through visual recognition of the number on the sole of the club, or through other visual recognition means, such as 2D or 3D barcodes, QR Codes, Aztec Codes, Data Matrix codes, etc), RFID, or Near-Field Communications.

Referring to FIG. **10**, in one configuration, the enhanced image may further include a putting aid **950** that may assist the user in reading the curvature and/or undulations of the green. Such a putting aid **950** may include a slope grid **952** and/or an ideal trajectory line **954**, which, if followed, would cause the ball to roll into the cup **956**. In one configuration, the slope grid **952** may include a plurality of virtual water beads **958** that may flow along the grid lines according to the absolute slope of the green **960** along the line (i.e., where a steeper gradient would result in a faster moving water bead **958** along the grid line). In another configuration, the putting aid **950** may include, for example at least one of a plurality of arrows aligned with a gradient of the green (and pointing in a downhill direction) and an indicator, such as a ball or cursor, that translates in a direction aligned with the gradient of the green. In this manner, the golfer may easily visualize whether he/she is putting uphill or downhill, and whether the ball may break to the right or to the left. The ideal trajectory **954** may take into account the slope of the green **960**, and the respective locations of the ball and cup **956**.

In the enhanced image examples provided in FIGS. **9**B, **9**C, and **10**, the ability to project an image on the ground requires an understanding of the topology of the ground relative to the eyeglasses **102**. In one configuration, the topology of the golf course may be uploaded to the system **100**, either prior to the start of the round, or in near-real time. The processor **202** may then pattern match the perceived topology within the more detailed, uploaded topology to align the two coordinate frames. This alignment may use GPS, visual recognition, and/or LIDAR, to identify perspective cues and/or one or more fiducials to position and orient the glasses in three dimensions within the topographical model. Using the known position and orientation of the eyeglasses **102**, the processor **202** may construct a perspective view of the topology from the point of view of the user. This perspective view of the topology may then be synchronized with the field of view of the user (such as may be digitally perceived via the camera **204**) and the processor **202** may display the visual overlays/enhanced imagery via the eyeglasses **102** in a manner that makes it appear to rest on the ground or objects as desired. For example, in a green reading context, the one or more putting aids **950** may be displayed such that they are coincident with the perceived portion of the green **960**.

In another configuration, rather than having the topographical information uploaded from an external database, it may instead be acquired in near-real time via one or more sensors disposed on the eyeglasses **102**. For example, in one embodiment, the eyeglasses **102** may include a LIDAR sensor (e.g., which may be used with the golf ball tracking system **200**). The LIDAR sensor may scan the proximate terrain with a sweeping laser (i.e., ultraviolet, visable, or near-infrared) to determine the distance between the sensor and each sampled point. The processor **202** may then skin the collection of points to form a model of the perceived topology.

When used to assist the user in reading the green **960**, the system **100** may dynamically adjust to display the nearest green. In one configuration, the processor **202** may, for example, continuously receive an indication of the location of the user, such as from the user tracking system **206**. Using this, the processor **202** may identify one of the plurality of

stored greens that is closest to the user. The processor **202** may then display a representation of the topology of the identified green **960** via the heads up display glasses, within the field of view of the user (i.e., either an overhead view or a perspective view). During a round of golf, this may allow a user to see the contours of the green as he is readying for an approach shot, as well as while putting.

While FIGS. **9**B, **9**C, and **10** schematically illustrate enhanced images before a shot, and FIG. **6** schematically illustrates an enhanced image during a shot, FIGS. **7** and **11** schematically illustrate enhanced images after a shot. As shown in FIG. **11**, following a shot, the system **100** may textually display statistics that relate to both the previous shot **1000** (i.e., shot statistics **1000**) and to more general play statistics **1002**. The play statistics **1002** may be statistics that are aggregated either just for that particular round, or over a longer duration such as a season. In addition to displaying statistics following the shot, the system **100** may also maintain a ball flight trace **1004** within the enhanced image for a predetermined amount of time.

Statistics relating to the previous shot **1000** may include, for example, initial ball speed **1006**, spin rate **1008**, carry **1010**, and/or remaining distance to the pin **1012**. Play statistics **1002** may include, for example, total number of strokes for the round **1014**, score relative to par **1016**, fairways hit **1018**, greens in regulation **1020**, and/or average number of puts **1022**.

The shot statistics **1000** may be directly acquired through the one or more sensors disposed on the eyeglasses **102**, within the ball, or on an associated device (e.g., a launch monitor), or may be determined by the processor **202** through, for example, an analysis of the ball flight/trajectory. The play statistics **1002**, however, may each be maintained in memory associated with the system **100** and updated following each shot. While certain play statistics **1002** (e.g., total strokes **1014** and average number of putts **1022**) may be easily aggregated simply by observing the user, others require the processor **202** to have an understanding of the course. For example, a user's score relative to par **1016** requires the system **100** to have knowledge of the course scorecard. Likewise, fairways hit **1018** and greens in regulation **1020** may require the system **100** to have knowledge of the physical layout of the course. To facilitate this knowledge, in one configuration, a digital rendering of the course (i.e., layout and/or topology) and/or scorecard may be uploaded to the system **100** prior to beginning the round. This layout and/or topology may be the same data that is uploaded, for example, to enable the system **100** to project imagery onto the ground within the user's real world view.

In addition to the above described game-play capabilities, the system **100** may further be configured in a practice mode, such as schematically illustrated via the enhanced display **1050** provided in FIG. **12**. Practice mode may be particularly useful, for example, on a driving range, where the user may hit a plurality of golf balls in succession using a single golf club. In this embodiment, the system **100** may maintain shot statistics **1000** on each of the plurality of golf balls that are hit by one or more golf clubs. The shot statistics **1000** may be grouped and averaged on a club-by-club basis, which may then be displayed via the eyeglasses **102** as specific club statistics **1052** for a particular club. These statistics may be displayed for an individual club, such as when the user draws the club from his/her bag or immediately after a shot. Alternatively, the club statistics **1052** may be displayed for a plurality of clubs, such as in a table format. Displaying multiple clubs at once may educate the user about the variance and/or differences between clubs of slightly different lofts. For example, if a user was presently using a 5-iron, the system may display club statistics for the 5-iron, as well as for the 4-iron and 6-iron.

The club statistics **1052** for a particular club may include, for example, an average carry distance **1054**, an average total distance **1056**, and an accuracy metric **1058**. The accuracy metric **1058** may attempt to characterize the amount of spray (i.e., a lateral deviation from an intended landing spot) that the user imparts to each of his/her respective clubs. For example, the accuracy metric **1058** may correspond to a width of a landing zone that is defined by the landing position of each of the plurality of golf balls hit by a particular club. Alternatively, it may represent a one standard deviation width of a distribution of landing positions for each of the plurality of golf balls.

In one configuration, the shot statistics **1000** and/or club statistics **1052** within practice mode may be determined either directly by sensors provided with the system **100** (e.g., sensors disposed on the eyeglasses **102**), or via ancillary hardware (e.g. a launch monitor) that is in digital communication with the system **100**.

In addition to maintaining the club statistics **1052** while in practice mode, the system **100** may also graphically represent a plurality of prior shots as traces **1062** via the enhanced display **1050**. The system **100** may also be configured to display an inlaid image **1064** within the user's field of view that represents the plurality of traces **1062** from a direction that is perpendicular to each ball's respective flight path. In this manner, the user may visually assess his/her tendencies to spray the ball (e.g., via the traces **1062** provided in the primary portion **1066** of the enhanced display **1050**), as well as the typical flight path/height of each respective shot (e.g., via the traces **1062** provided in the inlaid image **1064**). As mentioned above, in one configuration, the system **100** may know which club the user is hitting either by direct user input, or by visually recognizing the number on the sole of the club as the user selects it from his/her bag. In this manner, the processor may group the one or more computed shot statistics according to a detected identifier on the club, and then compute the one or more club statistics **1052** for a particular golf club from the one or more shot statistics **1000** that are grouped/associated to a single detected identifier.

If a user trains the system **100** to understand the user's various club statistics **1052**, then the system **100** may also be configured in an enhanced virtual caddy mode. In this mode, the system **100** may instruct the user both where to aim and which club to use. For example, as schematically shown in the enhanced view **1100** provided in FIG. **13**, in one configuration, the system **100** may provide a textual graphic **1102** of the optimal club for a given shot. Additionally, the system **100** may project a target **1104** at a position on the course (i.e., via the eyeglasses **102**) where the user should aim with that respective club. The target **1104** may be, for example, a dot or cross-hair that is illustrated at the desired landing spot, or may be an illustrated post or flag stick that graphically appears to be sticking out of the ground at the desired landing spot. The target **1104** may be positioned at the user's statistical mean landing spot for the club suggested. Additionally, the system **100** may project, for example, a 1-standard deviation accuracy circle **1106** onto the grass around the target **1102**. In this manner, the user may quickly identify whether certain hazards may be in play for that shot.

In the virtual caddy mode, the user may either pre-select his/her intended degree of risk prior to the round and/or may be able to change the desired risk level on a shot-by-shot basis. The risk level may be displayed via the eyeglasses **102** as a textual risk indicator **1108** prior to the shot. The level of

risk may serve as an input into an optimization routine performed by the processor **202**, and may influence both the club that the system **100** selects and the positioning of the target **1104** on the course. More specifically, the level of risk may adjust a weighting parameter in an optimization routine that seeks to minimize both the remaining distance to the hole and the statistical likelihood that a hazard will be in play (i.e., longer hitting woods/irons typically have a larger spray, which may increase the likelihood of bringing hazards into play (based on the design of the hole); shorter hitting wedges/irons have a narrower spray and can be more accurately aimed, though lack the hitting distance of the longer irons/woods).

In one configuration, an optimization method may begin by determining the most optimal target for each club, based on the course layout, the user's current position, and the stored club statistics **1052**. Each optimal target for a club may be disposed at a location on the course that is spaced from the location of the user by a distance that is equal to the average total distance for the respective club used (i.e., where average total distance is a club statistic that is previously stored in memory associated with the processor). To choose the specific heading for each optimal target, the processor may then find a location that provides the most ideal combination of lie and remaining distance to the pin.

More specifically, in determining the optimal target, the system **100** may score each type of lie within a statistical circle around the target, corresponding to a probable/statistical landing zone and/or derived from the accuracy metric for the respective club. For example, out of bounds and water hazards may have a score of 0.0; flat, unobstructed fairway may have a score of 1.0; and obstructed shots, sand, long rough, medium rough, short rough, and uneven lies may have differing scores that range between 0.0 and 1.0. The processor may then integrate the lie score (or may average the lie score) across the statistical circle to determine an aggregate lie score. Using this scoring, the processor **202** may determine the most optimal target for each club that provides the most ideal lie (i.e., in the scoring described above, the ideal lie would maximize the aggregate lie score), while also minimizing the remaining distance to the hole. Such a determination may occur using a first risk-weighted optimization that operates according to a first weighting parameter that may generally favor an improved lie over a minimized distance (i.e., where distance may factor in, for example, in deciding between two targets with identical lies, and in preferring shots toward the hole rather than away from the hole).

Once the most optimal target is selected for each club, the processor **202** may determine a new risk-weighted score for each club that combines a remaining distance to the hole for an optimized target with the aggregate lie score for the optimized target. This determination may be based on second weighting factor that is selected by the user to indicate the user's predetermined risk level. In this manner, a high risk would more heavily favor a minimum remaining distance, while a low risk would more heavily favor a more ideal lie. Once a risk-weighted score is determined for each club, the club having the highest risk-weighted score may be suggested to the user as a textual graphic **1102**, and the optimal target **1104** may be displayed in a proper position within the enhanced view. Additionally, in an embodiment, the statistical landing zone may be displayed as a circle around the target. In other configurations, the user may further be able to specify (or the system **100** may deduce) preferred approach distances, which may also affect the optimization.

Finally, FIG. **14** schematically illustrates a method **1200** that may be performed by the processor **202**. This method **1200** includes functionality that may exist in practice mode **1300**, and also during a round before a shot **1400**, during a shot **1500**, and after a shot **1600**. As shown, during practice mode **1300**, the processor **202** may begin by determining a club that is being used at **1302**. This may entail either receiving a user input that is indicative of the club, or by receiving a visual indication of a number provided on a sole of the club from a visual sensor associated with the eyeglasses **102**.

Once the club is determined at **1302**, the processor **202** may monitor the trajectory of a struck golf ball at **1304**, determine one or more shot statistics **1000** at **1306**, display the one or more determined shot statistics **1000** via the eyeglasses **102** at **1308**, and update the one or more club statistics **1052** at **1310**. In one configuration, steps **1304** and **1306** may be performed using input from one or more sensors disposed, for example, on the eyeglasses **102**. In another configuration, steps **1304** and **1306** may be performed using input obtained from an ancillary device, such as a launch monitor, that is in digital communication with the processor **202**. In this instance, the term processor **202** is intended to encompass both configurations, and may include multiple computing devices in digital communication.

Following a given shot, the processor **202** may determine if a new club is selected at **1312**. If so, it may revert back to step **1302**, or else may wait for the next shot at **1304**. The club statistics may then be stored in memory **1700** associated with the system **100** for subsequent use.

Prior to a round of golf, the system **100** may be initialized at **1702** by uploading course statistics, course layout and/or topology, and/or a course scorecard (i.e., collectively "course information") from an external database **1704** to the processor **202**. Additionally, during this initialization step **1702**, the user's club statistics **1052** may be made available to the processor **202** from memory **1700**. While in one configuration, the club statistics **1052** may be derived from a practice mode using the present system, in another configuration the club statistics **1052** may be uploaded to the memory **1700** via any commercially available 3rd party devices **1706**, such as golf simulation devices or launch monitors.

Prior to a shot, the processor **202** may monitor a user's real-time location at **1402**. This may include monitoring one or more GPS receivers, RF triangulation modules, and optical sensors to determine the location of the user within the course. If the user is not stationary (at **1404**), then the processor **202** may continue monitoring the user's position. If the user's location has become stationary, then at **1406**, the processor **202** may determine the distance between the user and any object, hazard, landmark, or course feature (e.g., fairway, rough, green) that may be within a predetermined distance of the user and/or between the user and the furthest portion of the green from the user. This determination may occur using GPS coordinates and/or one or more optical sensors, such as LIDAR.

Following the distance determination at **1406**, the processor may perform one or more of the following: display one or more of the determined distances to the user via the eyeglasses **102** (at **1408**); display one or more yardage-based distance lines **924**, **926**, **928** to the user via the eyeglasses **102** (at **1410**); display one or more club-based distance lines **930**, **932**, **934** to the user via the eyeglasses **102** (at **1412**); perform a risk-weighted optimization to determine at least one of an optimal club and an optimal target (at **1414**); display an optimal club to the user via the eyeglasses **102** (at **1416**); display an optimal target to the user via the eyeglasses **102** (at **1418**); display the user's statistical landing zone about the target via the eyeglasses **102** (at **1420**); and display a putting aid to the user via the eyeglasses **102** (at **1422**), where the

putting aid includes either a displayed grid (at **1424**) or an ideal putting trajectory (at **1426**).

During the shot **1500**, the processor **202** may receive a data input corresponding to the ball dynamics (at **1502**) and/or the user's view (at **1504**). From this input, the processor **202** may then determine one or more shot statistics **1000** (at **1506**). The determined shot statistics **1000** may include, for example, ball speed, **1006**, spin rate **1008**, carry **1010**, and remaining distance to the pin **1012**, and may be determined from the observed ball trajectory, the observed club impact angle/speed, or from an associated launch monitor or ancillary device/sensor. Additionally, during the ball flight, the processor **202** may display a visual indicator, trace, or other overlay via the eyeglasses **102** that corresponds with the actual, observed flight of the ball (at **1508**).

After the shot **1600**, the processor **202** may display the one or more determined shot statistics **1000** via the eyeglasses **102** (at **1602**). Additionally, the processor **202** may then compute one or more play statistics **1002** (at **1604**), and may display the one or more computed play statistics **1002** to the user via the eyeglasses **102** (at **1606**). The processor **202** may then recompute the club statistics **1052** (at **1608**) and resume monitoring the user's real-time location at **1402** to prepare for the next shot.

While the use of the eyeglasses **102** is the preferred manner of practicing the present invention, in alternate configurations, one or more of the steps of displaying the various pre-shot distances and/or post-shot shot statistics **1000** or play statistics **1002** may occur using the interface **114** (shown in FIG. **1**), which may include a hand held device, such as a smart phone or tablet. Additionally, in a further embodiment, pre-shot distances and/or post-shot shot statistics **1000** or play statistics **1002** may be superimposed on a video stream that is captured by a camera on the hand held device, and displayed by an LCD/OLED/LED display device integrated within the hand held device. In this embodiment, the glasses may not be strictly required.

While various embodiments of the invention have been described, the description is intended to be exemplary, rather than limiting and it will be apparent to those of ordinary skill in the art that many more embodiments and implementations are possible that are within the scope of the invention. Accordingly, the invention is not to be restricted except in light of the attached claims and their equivalents. Also, various modifications and changes may be made within the scope of the attached claims.

The invention claimed is:

1. A golf aid system including a practice mode for use while hitting a plurality of golf balls with a golf club, the golf aid system comprising:

a golf ball tracking system for tracking a plurality of golf ball trajectories, each one of the plurality of trajectories corresponding to a respective one of the plurality of golf balls being hit by the golf club;

a heads up display configured to be worn on the user's head and display an image within a field of view of the user;

a processor in communication with the golf ball tracking system and the heads up display device, the processor configured to:

compute one or more shot statistics for each one of the plurality of trajectories, wherein the one or more shot statistics include at least one of an initial ball speed, a spin rate, a total distance, and a carry distance;

display the one or more computed shot statistics within the field of view of the user via the heads up display following each one of the plurality of golf balls being hit by the golf club, wherein the displayed shot statistics correspond to an immediately preceding trajectory; and

display a plurality of traces within the field of view of the user via the heads up display, wherein each one of the plurality of traces corresponds to a respective one of the plurality of trajectories.

2. The golf aid system of claim **1**, wherein the processor is further configured to:

compute one or more club statistics for the golf club from the computed shot statistics, wherein the one or more club statistics include at least one of an average carry distance for the golf club, an average total distance for the golf club, and an accuracy metric for the golf club; and

display the one or more computed club statistics within the field of view of the user via the heads up display.

3. The golf aid system of claim **2**, further comprising a camera disposed on the heads up display and configured to capture an image including a portion of the user's field of view;

wherein the processor is further configured to:

receive the captured image from the camera;

detect an identifier on the golf club from the received image, the identifier corresponding to a loft angle of the club;

group the one or more computed shot statistics according to a detected identifier;

wherein the processor computes the one or more club statistics for the golf club from the one or more shot statistics grouped to a single detected identifier.

4. The golf aid system of claim **3**, wherein the processor is configured to detect an identifier on the golf club from the received image by optically recognizing a number or a letter disposed on a sole of the golf club.

5. The golf aid system of claim **2**, wherein the accuracy metric corresponds to a width of a landing zone defined by a landing position of each of the plurality of golf balls.

6. The golf aid system of claim **5**, wherein the accuracy metric is a one standard deviation width of a distribution of landing positions that includes the landing position of each of the plurality of golf balls.

7. The golf aid system of claim **2**, wherein the golf club is a first golf club; and

wherein the processor is further configured to compute one or more club statistics for a second golf club.

8. A golf aid system including a practice mode for use while hitting a first plurality of golf balls with a first golf club and while hitting a second plurality of golf balls with a second golf club, the golf aid system comprising:

a golf ball tracking system for tracking a first plurality of golf ball trajectories each one of the first plurality of golf ball trajectories corresponding to a respective one of the first plurality of golf balls being hit by the first golf club, and for tracking a second plurality of golf ball trajectories each one of the second plurality of golf ball trajectories corresponding to a respective one of the second plurality of golf balls being hit by the second golf club;

a heads up display configured to be worn on the user's head and display an image within a field of view of the user; and

a processor in communication with the golf ball tracking system and the heads up display device, the processor configured to:

compute a first club statistic for the first golf club from the tracked first plurality of golf ball trajectories;

compute a second club statistic for the second golf club from the tracked second plurality of golf ball trajectories; and

display at least one of the first club statistic and the second club statistic within the field of view of the user via the heads up display;

wherein the first club statistic includes at least one of an average carry distance for the first golf club, an average total distance for the first golf club, and an accuracy metric for the first golf club; and

wherein the second club statistic includes at least one of an average carry distance for the second golf club, an average total distance for the second golf club, and an accuracy metric for the second golf club.

9. The golf aid system of claim **8**, further comprising a camera disposed on the heads up display and configured to capture an image including a portion of the user's field of view;

wherein the processor is further configured to:

receive a plurality of captured images from the camera;

detect a first identifier corresponding to the first golf club from the plurality of received images;

detect a second identifier corresponding to the second golf club from the plurality of received images; and

use at least one of the first identifier and the second identifier to associate a newly tracked trajectory with one of the first plurality of golf ball trajectories and the second plurality of golf ball trajectories.

10. The golf aid system of claim **9**, wherein the processor is configured to detect one of the first and second identifiers from the plurality of received images by optically recognizing a number or a letter.

11. The golf aid system of claim **9**, wherein the accuracy metric corresponds to the width of a landing zone defined by a landing position of each golf ball of one of the first plurality of golf balls and the second plurality of golf balls.

12. The golf aid system of claim **9**, wherein the accuracy metric is a one standard deviation width of a distribution of landing positions that includes the landing position of each golf ball of one of the first plurality of golf balls and the second plurality of golf balls.

13. The golf aid system of claim **9**, wherein the processor is further configured to:

compute a first shot statistic for the first golf club from the tracked first plurality of golf ball trajectories;

compute a second shot statistic for the second golf club from the tracked second plurality of golf ball trajectories;

wherein each of the first shot statistic and the second shot statistic includes at least one of an initial ball speed, a spin rate, a total distance, and a carry distance; and

display the one or more computed shot statistics within the field of view of the user via the heads up display.

14. A non-transitory, computer readable medium having stored thereon instructions for execution by a processor to perform steps comprising:

receiving an indication of a tracked flight of a plurality of golf ball trajectories from a sensor, each one of the plurality of trajectories corresponding to a respective one of a plurality of golf balls being hit by a golf club;

computing one or more shot statistics for each one of the plurality of trajectories; wherein the one or more shot statistics include at least one of an initial ball speed, a spin rate, a total distance, and a carry distance;

displaying the one or more computed shot statistics within the field of view of the user via a heads up display configured to be worn on the user's head; and

displaying a plurality of traces within the field of view of the user via the heads up display, wherein each one of the plurality of traces corresponds to a respective one of the plurality of trajectories.

15. The computer readable medium of claim **14**, further comprising instructions for causing the processor to perform steps comprising:

computing one or more club statistics for the golf club from the computed shot statistics, wherein the one or more club statistics include at least one of an average carry distance for the golf club, an average total distance for the golf club, and an accuracy metric for the golf club; and

displaying the one or more computed club statistics within the field of view of the user via the heads up display.

16. The computer readable medium of claim **15**, further comprising instructions for causing the processor to perform steps comprising:

receiving an image from a camera disposed in communication with the heads up display and corresponding to the field of view of the user;

detecting an identifier on the golf club from the received image, the identifier corresponding to a loft angle of the club;

grouping the one or more computed shot statistics according to a detected identifier; and

wherein computing the one or more club statistics for the golf club includes computing the one or more club statistics from the one or more shot statistics grouped to a single detected identifier.

17. The computer readable medium of claim **16**, wherein detecting an identifier on the golf club from the received image includes optically recognizing a number or a letter disposed on a sole of the golf club.

18. The computer readable medium of claim **15**, wherein the accuracy metric corresponds to a width of a landing zone defined by a landing position of each of the plurality of golf balls.

19. The computer readable medium of claim **15**, wherein the accuracy metric is a one standard deviation width of a distribution of landing positions that includes the landing position of each of the plurality of golf balls.

20. The computer readable medium of claim **15**, wherein the golf club is a first golf club; and

further comprising instructions for causing the processor to compute one or more club statistics for a second golf club.

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